

流体力学

Fluid Mechanics



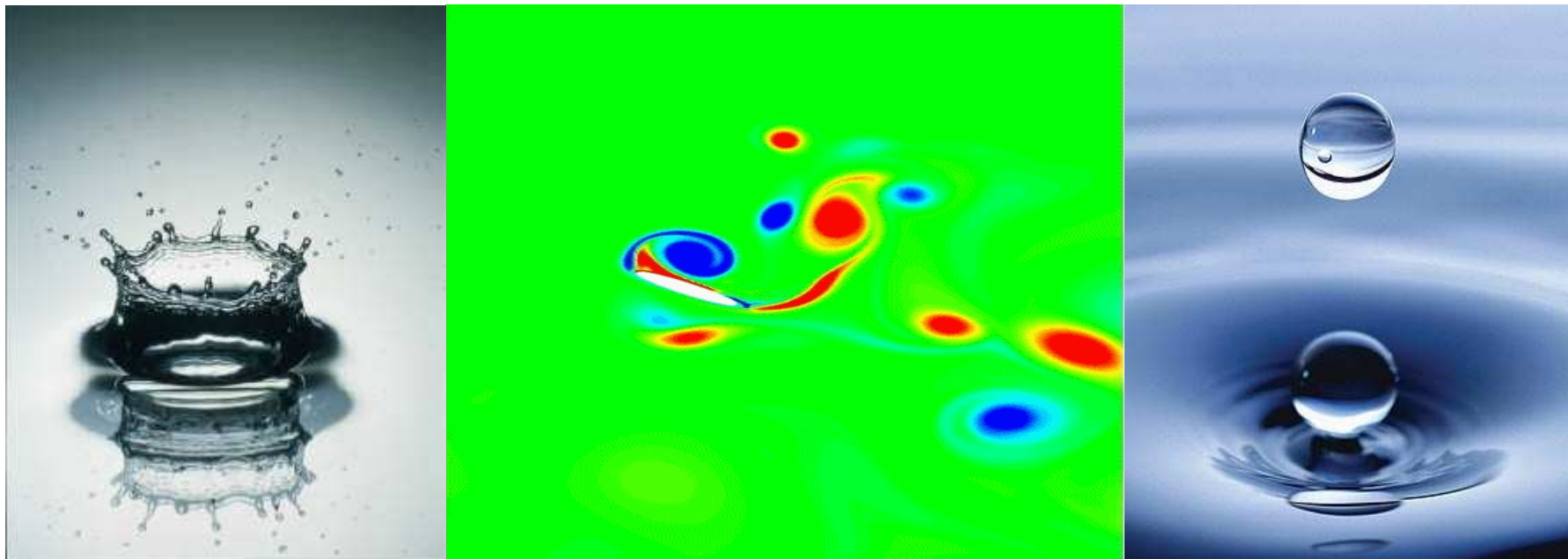
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School of Energy and Power Engineering
Jiangsu University

Computational & Applied Fluid Engineering (CAFÉ) Lab



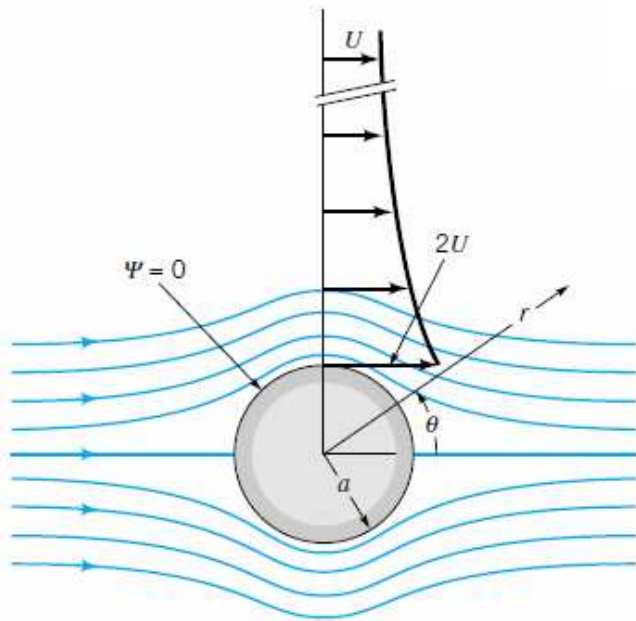
欢迎大家进入奥妙无穷、绚丽多彩的
流体力学世界!



参考教材:《流体力学》(第三版) 江苏大学 罗惕乾主编 机械工业出版社 2007
《Fundamentals of Fluid Mechanics》 Bruce R. Munson, Donald F. Yong, Theodore H. Okiishi



Inviscid Flow Around a Circular Cylinder



$$F_x = - \int_0^{2\pi} p_s \cos \theta a d\theta$$

$$F_y = - \int_0^{2\pi} p_s \sin \theta a d\theta$$

$$F_x = 0 \quad F_y = 0$$

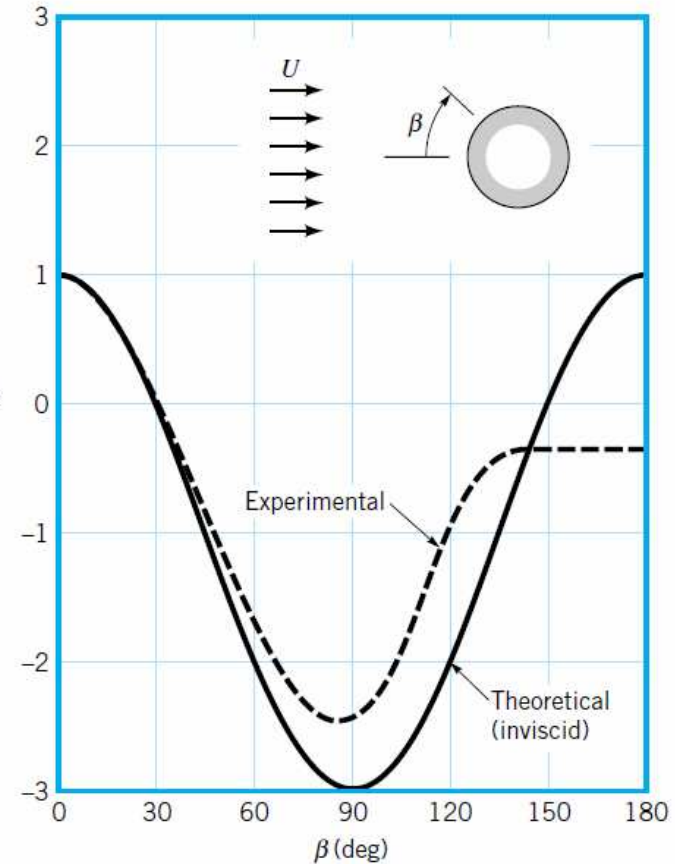
d'Alembert paradox

Jean LeRond
d'Alembert

(1717-1783)

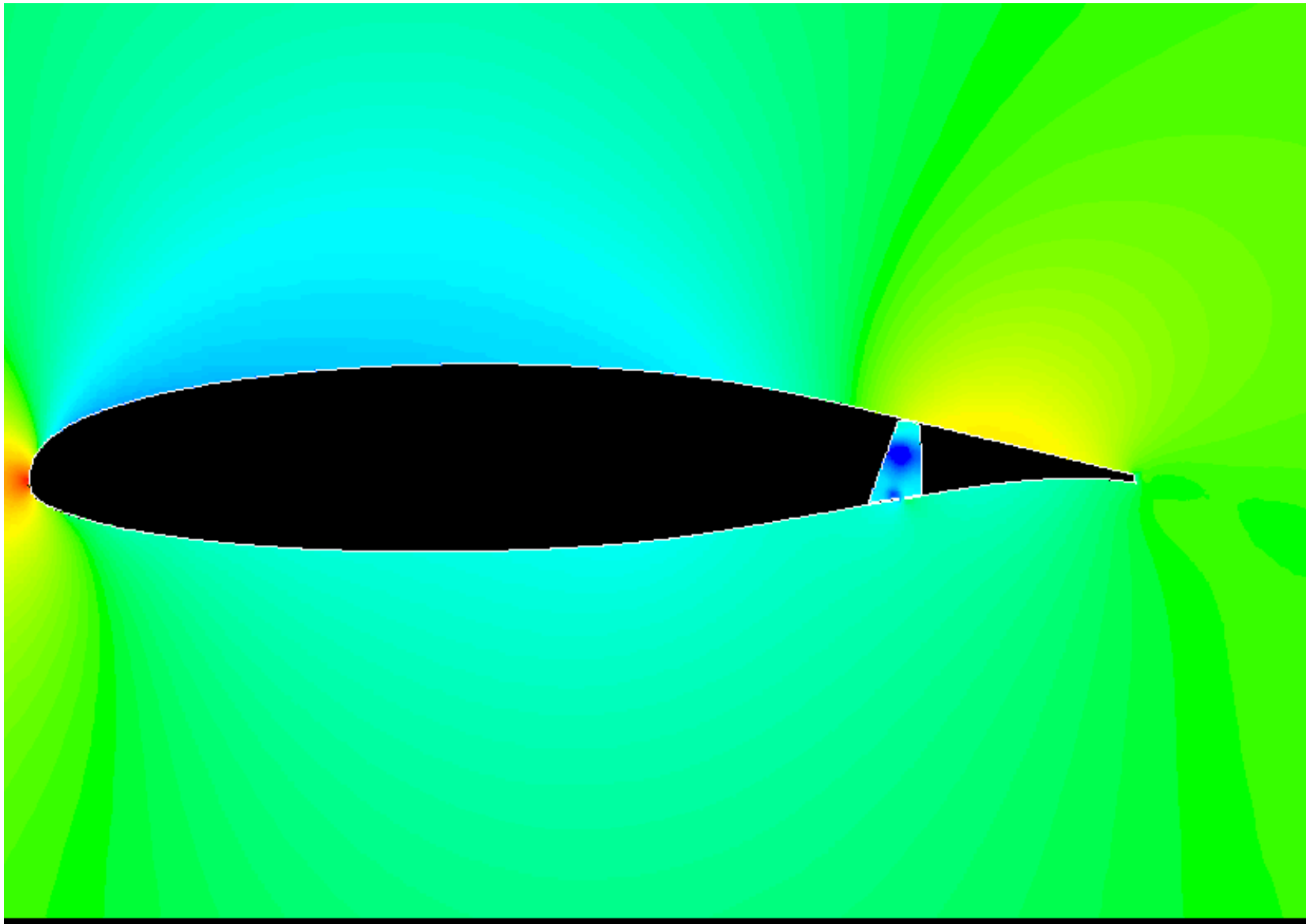
达朗贝尔悖论 (佯谬)

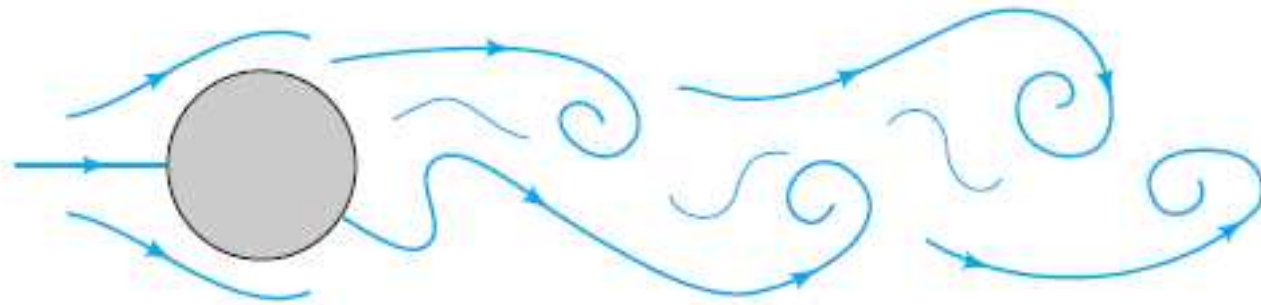
$$p_s = p_0 + \frac{1}{2}\rho U^2(1 - 4 \sin^2 \theta)$$



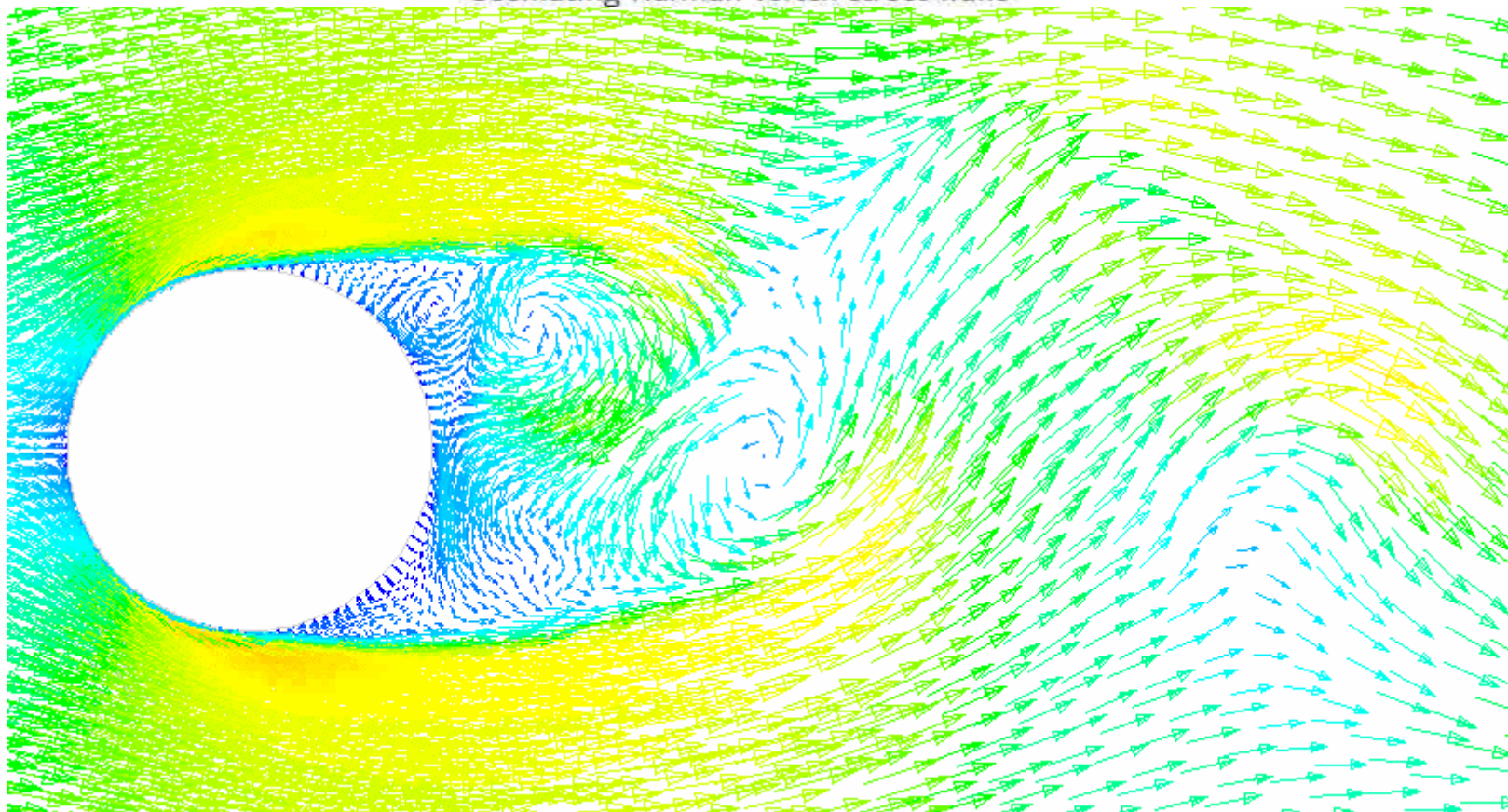
A comparison of theoretical (inviscid) pressure distribution on the surface of a circular cylinder with typical experimental distribution.







Oscillating Karman vortex street wake



Navier–Stokes equations, named in honor of the French mathematician **L. M. H. Navier** (1758–1836) and the English mechanician **Sir G. G. Stokes** (1819–1903), who were responsible for their formulation.



纳维 (L. Navier, 1785–1836, 法国数学家)

N-S equations



斯托克斯 (G. Stokes, 1819–1903, 英国力学家)



6.1 Forces Acting on Differential Elements

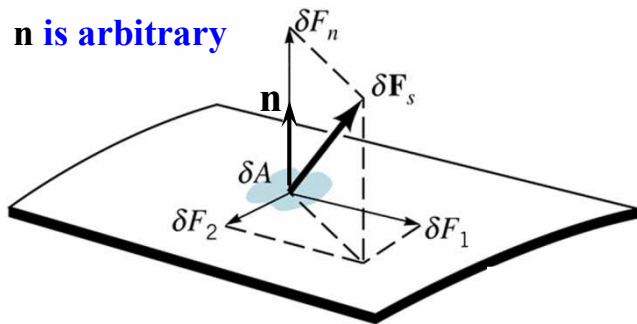
Two types of forces: **Body** and **Surface Forces**

Body forces

$$\delta \mathbf{F}_B = \delta m \cdot \mathbf{g}$$

Surface force $\delta \mathbf{F}_S$

n is arbitrary



$$\sigma_n = \lim_{\delta A \rightarrow 0} \frac{\delta F_n}{\delta A}$$

Normal stress

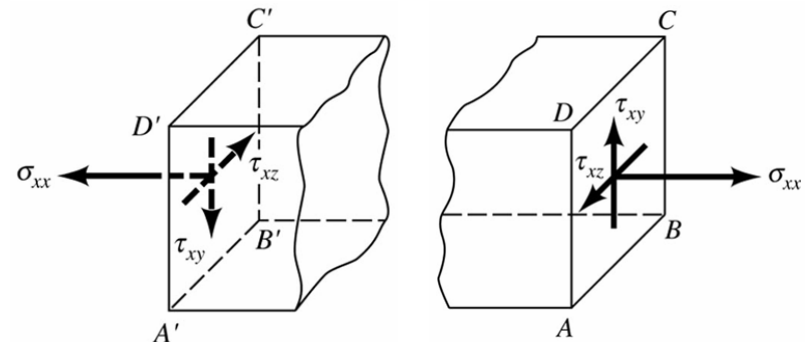
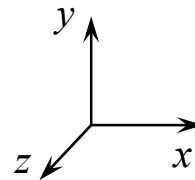
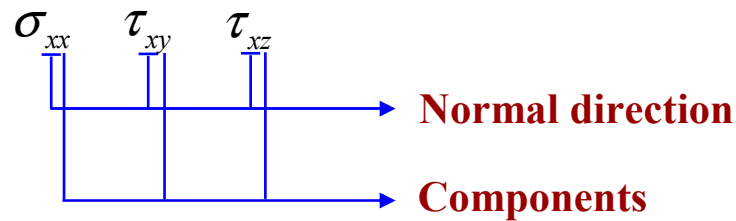
$$\tau_1 = \lim_{\delta A \rightarrow 0} \frac{\delta F_1}{\delta A}$$

$$\tau_2 = \lim_{\delta A \rightarrow 0} \frac{\delta F_2}{\delta A}$$

Shearing stresses

1 subscript can not tell the exact direction

Double subscripts for normal and shearing stresses



6.1 Forces Acting on Differential Elements

Total force on the element in the x-direction

$$\delta F_{S,x} = (\sigma_{xx} + d\sigma_{xx}) dydz - \sigma_{xx} dydz + (\tau_{yx} + d\tau_{yx}) dx dz - \tau_{yx} dx dz + (\tau_{zx} + d\tau_{zx}) dx dy - \tau_{zx} dx dy$$

$$\delta F_{S,x} = d\sigma_{xx} dydz + d\tau_{yx} dx dz + d\tau_{zx} dx dy$$

$$d\sigma_{xx} = \frac{\partial \sigma_{xx}}{\partial x} dx + \frac{\partial \sigma_{xx}}{\partial y} dy + \frac{\partial \sigma_{xx}}{\partial z} dz \quad d\tau_{yx} = \frac{\partial \tau_{yx}}{\partial y} dy \quad d\tau_{zx} = \frac{\partial \tau_{zx}}{\partial z} dz$$

$$\delta F_{S,x} = \frac{\partial \sigma_{xx}}{\partial x} dx dy dz + \frac{\partial \tau_{yx}}{\partial y} dx dy dz + \frac{\partial \tau_{zx}}{\partial z} dx dy dz$$

$$\delta F_{S,y} = \frac{\partial \tau_{xy}}{\partial x} dx dy dz + \frac{\partial \sigma_{yy}}{\partial y} dx dy dz + \frac{\partial \tau_{zy}}{\partial z} dx dy dz$$

$$\delta F_{S,z} = \frac{\partial \tau_{xz}}{\partial x} dx dy dz + \frac{\partial \tau_{yz}}{\partial y} dx dy dz + \frac{\partial \sigma_{zz}}{\partial z} dx dy dz$$

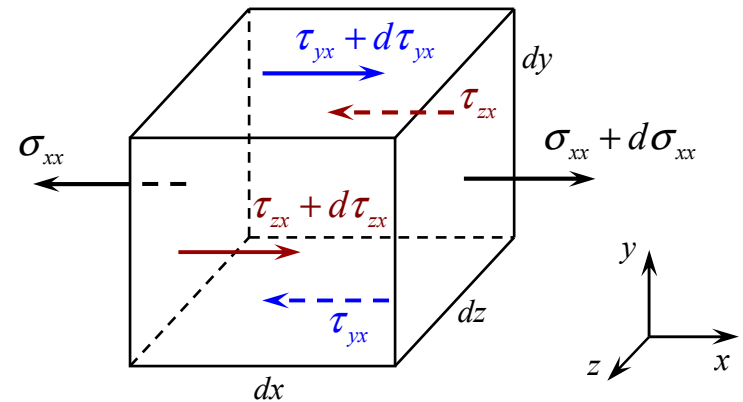
$$\delta \mathbf{F}_S = \delta F_{S,x} \mathbf{i} + \delta F_{S,y} \mathbf{j} + \delta F_{S,z} \mathbf{k}$$

$$\delta \mathbf{F}_B = \delta m \cdot \mathbf{g} = \delta m \cdot g_x \mathbf{i} + \delta m \cdot g_y \mathbf{j} + \delta m \cdot g_z \mathbf{k}$$

$$\delta \mathbf{F} = \delta \mathbf{F}_S + \delta \mathbf{F}_B = \delta m \cdot \mathbf{a} = \rho dx dy dz \cdot \mathbf{a}$$



Stresses in the x-direction



$$\frac{\partial \sigma_{xx}}{\partial x} dx dy dz + \frac{\partial \tau_{yx}}{\partial y} dx dy dz + \frac{\partial \tau_{zx}}{\partial z} dx dy dz + \rho dx dy dz \cdot g_x = \rho dx dy dz \cdot a_x$$

$$x: \frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \tau_{yx}}{\partial y} + \frac{\partial \tau_{zx}}{\partial z} + \rho g_x = \rho \left(\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right)$$

$$y: \frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_{yy}}{\partial y} + \frac{\partial \tau_{zy}}{\partial z} + \rho g_y = \rho \left(\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} \right)$$

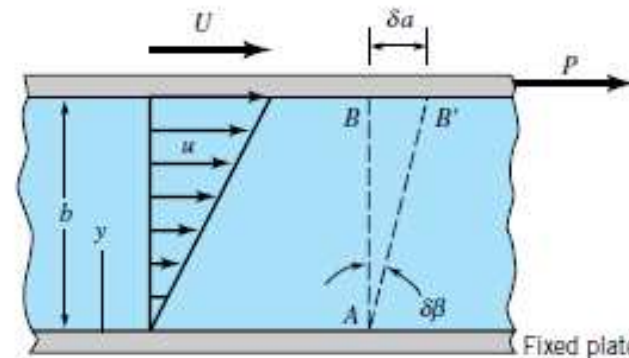
$$z: \frac{\partial \tau_{xz}}{\partial x} + \frac{\partial \tau_{yz}}{\partial y} + \frac{\partial \sigma_{zz}}{\partial z} + \rho g_z = \rho \left(\frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} \right)$$

应力形式的动量方程

6.2 Navier-Stokes (N-S) Equations

$$\begin{aligned}
 x: \quad & \frac{\partial \sigma_{xx}}{\partial x} + \frac{\partial \tau_{yx}}{\partial y} + \frac{\partial \tau_{zx}}{\partial z} + \rho g_x = \rho \left(\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right) \\
 y: \quad & \frac{\partial \tau_{xy}}{\partial x} + \frac{\partial \sigma_{yy}}{\partial y} + \frac{\partial \tau_{zy}}{\partial z} + \rho g_y = \rho \left(\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} \right) \\
 z: \quad & \frac{\partial \tau_{xz}}{\partial x} + \frac{\partial \tau_{yz}}{\partial y} + \frac{\partial \sigma_{zz}}{\partial z} + \rho g_z = \rho \left(\frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} \right)
 \end{aligned}$$

Equations of Motion



Stress-Deformation Relationships

Constitutive equations (本构方程) $\tau = \mu \frac{du}{dy}$

$$\tau_{xy} = \tau_{yx} = \mu \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) \quad \sigma_{xx} = -p + 2\mu \frac{\partial u}{\partial x}$$

$$\tau_{yz} = \tau_{zy} = \mu \left(\frac{\partial v}{\partial z} + \frac{\partial w}{\partial y} \right) \quad \sigma_{yy} = -p + 2\mu \frac{\partial v}{\partial y}$$

$$\tau_{zx} = \tau_{xz} = \mu \left(\frac{\partial w}{\partial x} + \frac{\partial u}{\partial z} \right) \quad \sigma_{zz} = -p + 2\mu \frac{\partial w}{\partial z}$$

Viscous Fluids

$$\frac{\partial}{\partial x} \left(-p + 2\mu \frac{\partial u}{\partial x} \right) + \frac{\partial}{\partial y} \left(\mu \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) \right) + \frac{\partial}{\partial z} \left(\mu \left(\frac{\partial w}{\partial x} + \frac{\partial u}{\partial z} \right) \right) + \rho g_x = \rho \left(\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right)$$

$$\rho \left(\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right) = \rho g_x - \frac{\partial p}{\partial x} + \mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) + \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right)$$



6.2 Navier-Stokes (N-S) Equations

$$\rho \left(\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right) = \rho g_x - \frac{\partial p}{\partial x} + \mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) + \frac{\partial}{\partial x} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right)$$

Incompressible Flows $\nabla \cdot \mathbf{v} = 0$ $\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$

Navier-Stokes (N-S) Equations (*Viscous and Incompressible Flows*)

$$x: \rho \left(\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right) = - \frac{\partial p}{\partial x} + \rho g_x + \mu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right)$$

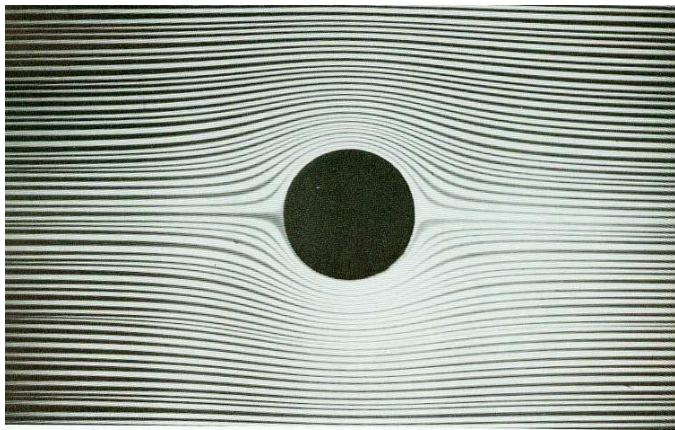
$$y: \rho \left(\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} \right) = - \frac{\partial p}{\partial y} + \rho g_y + \mu \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} \right)$$

$$z: \rho \left(\frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} \right) = - \frac{\partial p}{\partial z} + \rho g_z + \mu \left(\frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} \right)$$

$$\begin{cases} g_x - \frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \left(\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) = \frac{du}{dt} \\ g_y - \frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \left(\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} \right) = \frac{dv}{dt} \\ g_z - \frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \left(\frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} \right) = \frac{dw}{dt} \end{cases}$$

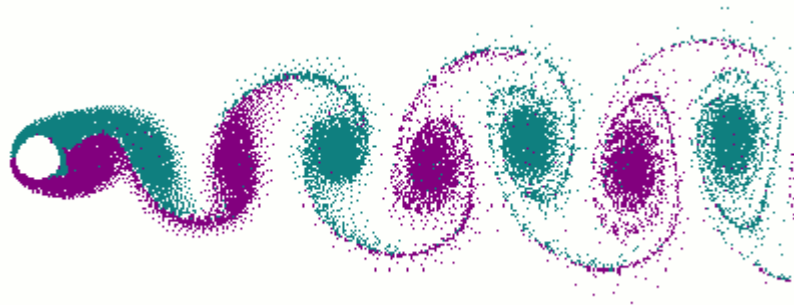
$$\mathbf{g} - \frac{1}{\rho} \nabla p + \nu \nabla^2 \mathbf{v} = \frac{d\mathbf{v}}{dt}$$





低速绕流圆柱的对称图像的优美

(优美) 对称, 比例, 简洁



卡门涡街的尺寸配比何等匀称!



战机翱翔天际的刚毅之美



大坝喷薄而出的壮阔之美





龙卷风和飞机尾涡在天空绘制的奇美画卷



痛并快乐着
让我们共同追寻流体力学之美!

谢谢大家!

